

Thermoelastic medium with swelling porous structure and impedance boundary under dual-phase lag

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ABSTRACT

This paper investigates the impact of dual phase latency caused by the reflection of plane waves that propagate in a swelling porous thermoelastic medium with an impedance boundary. Two transversal waves (SV_S , SV_F), a thermal wave (T), and two longitudinal waves (Ps and Pf) propagate with distinct velocities. Reflection coefficients are determined by the incidence of these waves, and energy ratios for reflected waves are calculated and illustrated using these amplitude ratios. In this particular instance, the current model was downsized to an LS model. It has been noted that the energy ratios acquired are significantly influenced by dual phase lag. The results that have been obtained may be beneficial in a variety of engineering problems that are related to structure.

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1. Introduction

The theory of thermoselasticity, which is characterized by a finite speed for thermal signals, has garnered significant attention in recent decades as a result of its potential relevance in the area of aerodynamic engineering and seismology. Lord and Shulman (1967) replaced the classical Fourier's law with a new wave type heat equation, which is also referred to as LS theory or extended thermoelastic theory. They employed only one thermal relaxation time. The microstructural interface effect is associated with the dual-phase lag model (DPL) in the rapid temporary heat process. Chandrasekharaiah (1998) was the first to introduce the dual phase lag model in the theory of thermos elasticity. Ramadan and AL-Nimr (2009) employed a dual phase lag model to investigate the reflection and the transmission phenomena of thermal waves in a two-layer slab with imperfect contact. Their findings indicated that the thermal contact resistance should be minimized in order to mitigate thermal stress. Abouelregal (2011) examined the influence of dual-phase lag parameters on the reflection of P and SV waves from magneto-thermoelastic solid half space. He found that the reflection coefficients are considerably affected by the magnetic field, but the thermal coupling parameter has the least impact. Singh (2012) obtained reflection coefficients as a result of the motion of waves in a dual-phase lag anisotropic thermoelastic solid half-space. Kumar (2012) investigated the reflection of plane waves in thermodiffusive elastic half-space with cavities. Sharma *et al.* (2013) explored the impact of micropolar thermoelastic solid with two temperatures on wave propagation, which is surrounded by strata of half spaces of inviscid liquid. Zenkour *et al.* (2013) have observed that dual phase lag has a more significant impact on the reflection of thermoelastic waves from isothermal and stress-free and boundaries than other thermoelastic theories.

Sharma *et al.* (2013, 2014) considered the reflection and refraction of plane waves in micropolar elastic solids. The uniqueness and reciprocal theorems for dual-phase lag thermoelastic theory were established by El-Karamany and Ezzat (2014) through the use of Laplace transformation. Kumar and Gupta (2015) proposed a dual phase lag diffusion model and augmented classical Fick law to investigate the reflection and refraction of waves at the boundary of thermoelastic and elastic diffusion media. Alla *et al.* (2016) employed a dual phase lag model to derive the expression of amplitude ratios resulting from the reflection of waves from the electro-magnetic thermoelastic half space. They then compared the results to those of

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the LS theory. In the context of a time differential dual phase lag thermoelastic model, Chirita (2017) established the results of continuous dependence and uniqueness.

Deswal *et al.* (2019) found that the reflection coefficients for the DPL model are modest in comparison to those of the LS theory. Kalkal *et al.* (2019) employed a dual phase lag model to analyse the impact of initial stress and fiber reinforcement on the reflection and transmission coefficients. Dahahb *et al.* (2019) conducted an investigation into the impact of gravity and rotation on an electro-magneto-thermoelastic medium. They found that the solutions derived for the LS and DPL models exhibit the same tendency along the z-axis. The non-local dual phase lag model (DPL) was introduced by Kumar *et al.* (2019) to investigate the impact of thermomass and thermoelastic properties on nan-scale heat transport. The authors concluded that the non-local dual phase lag model is more realistic than the dual phase model. Lata *et al.* (2020) analyzed the elastic properties of waves propagating in a magneto-thermoelastic medium using a dual phase lag model and obtained reflection coefficients. Kumar *et al.* (2021) performed a study on the influence of nonlocal, void, and micropolar parameters on the reflection of waves from the thermoelastic half space using a DPL model. They then compared the results to those obtained using the LS model.

Sharma and Khator (2021, 2022) investigated certain issues related to the generation of electricity from renewable sources. Sharma *et al.* (2022) investigated the impact of impedance parameters on the propagation of waves in a micropolar thermoelastic medium using a modified Green-Lindsay (GL) theory. Khan and Tanveer (2022) employ a dual phase latency model to determine the reflection and transmission coefficient of SV waves that are propagating at the solid-liquid interface. Kumar *et al.* (2023) investigated the influence of non-local dual phase latency and double porosity on the propagation of waves at the boundary of a double porous thermoelastic medium and an inviscid liquid half-space. Ma and Liu (2023) developed a non-local thermoelastic model and discovered that the deflection parameter of the nanoplate is reduced by the nonlocal heat parameter and increased by the nonlocal structural parameter. The impact of nonlocal triclinic micropolar thermoelastic medium on the reflection and transmission of the plane wave propagating at the interface with distinct elastic properties was obtained by Kumar *et al.* (2024). Additionally, they conducted a comparison between the phase velocity and energy ratios obtained from the DPL model and the LS theory. In order to investigate the influence of hall current and initial stress on micropolar thermoelastic theory under dual phase lag, Abouelregal and Rashid (2024) employed higher order time derivatives. In their study of the sensitivity of the heating process of thin metal films, Majchrzak and Mochnacki (2024) examined that the sensitivity of the temperature field remains high when the metal has a higher mean conductivity. In a transversely isotropic exponentially graded thermoelastic medium with cavities, Barak *et al.* (2024) investigated the impact of dual phase lag and non-local lag models. Additional issues concerning the reflection of waves under dual phase latency are detailed in (Deswal *et al.*, 2024; Punia *et al.*, 2024; Eraki *et al.*; 2024).

In the current study, the reflection of plane waves from the half space of a swelling porous thermoelastic medium with impedance boundary conditions under dual phase lag is studied. There are two longitudinal waves, a thermal wave, and two transversal waves that propagate at varying speeds. The numerical computation of reflection coefficients and energy ratios resulting from the incidence of each wave. The energy ratios in dual phase lag (DP) and LS model are compared numerically and presented through a graphical representation.

2. Fundamental Equations

Fundamental equations in swelling porous thermoelastic medium when body forces are ignored is given as Eringen (1994)

$$\mu u_{i,jj}^s + (\lambda + \mu) u_{j,ji}^s - \sigma^f u_{j,ji}^f + \xi^{ff} (\dot{u}_i^f - \dot{u}_i^s) + (\gamma^f - \alpha_0) \nabla T = \rho_0^s \ddot{u}_i^s \quad (2.1)$$

$$\mu_v \dot{u}_{i,jj}^f + (\lambda_v + \mu_v) \dot{u}_{j,ji}^f - \sigma^f u_{j,ji}^s - \sigma^{ff} u_{j,ji}^f - \xi^{ff} (\dot{u}_i^f - \dot{u}_i^s) - (\gamma^f + \alpha^f) \nabla T = \rho_0^f \ddot{u}_i^f \quad (2.2)$$

$$K^* \left(1 + \tau_T \frac{\partial}{\partial t} \right) \nabla^2 T = \left(1 + \tau_q \frac{\partial}{\partial t} + \frac{\tau_q^2}{2!} \frac{\partial^2}{\partial t^2} \right) (T_0 \alpha^f \nabla \cdot \dot{u}^f + \alpha_0 T_0 \nabla \cdot \dot{u}^s + \alpha_1 T_0 \dot{T}) + \zeta^f (\nabla \cdot \dot{u}^f + \nabla \cdot \dot{u}^s) \quad (2.3)$$

$$t_{ij}^s = (-\alpha_0 T - \sigma^f u_{r,r}^f + \lambda u_{r,r}^s) \delta_{ij} + \mu (u_{i,j}^s + u_{j,i}^s) \quad (2.4)$$

$$t_{ij}^f = (-\alpha^f T - \sigma^f u_{r,r}^s - \sigma^{ff} \nabla \cdot u^f + \lambda_v \dot{u}_{r,r}^f) \delta_{ij} + \mu_v (u_{i,j}^f + u_{j,i}^f) \quad (2.5)$$

2.1 Nomenclature

λ, μ	=	lame's parameters (N/m^2)
ρ_0^s, ρ_0^f	=	mass density in solid and fluid in natural state (Ns^2/m^4)
σ^f, σ^{ff}	=	dissipation constant (N/m^2)
ξ^{ff}	=	coupling coefficient (Ns/m^4)
λ_v, μ_v	=	viscosity coefficient (Ns/m^2)
T	=	temperature (K)

T_0	=	uniform temperature (K)
K^*	=	thermal conductivity (N/sK)
$\alpha^f, \alpha_0, \gamma^f$	=	material constants (N/m ² K)
α_1	=	material constant (N/m ² K ²)
τ_T	=	phase lag parameter of temperature gradient (s)
τ_q	=	phase lag parameter of heat flux (s)
ζ^f	=	material constant related to liquid (N/m ²)
t	=	time (s)
u^s, u^f	=	displacement in solid and liquid (m)
t_{ij}^s, t_{ij}^f	=	components of stress tensor in solid and liquid (N/m ²)
ω	=	angular frequency(rad/s)
k	=	wave number (m ⁻¹)
Z_1, Z_2, Z_3, Z_4	=	impedance parameters (Ns/m ³)
Z_5	=	impedance parameter (N/mK)
δ_{ij}	=	Kronecker delta function (dimensionless)

3. Problem formation and resolution

A homogeneous, isotropic swelling porous thermoelastic half-space has been taken into account. The origin of the rectangular cartesian coordinate system (x_1, x_2, x_3) is located at the boundary $x_3 = 0$, with the x_3 -axis pointing ordinarily into the medium. The intersection of the plane wavefront and the plane surface is represented by the x_2 -axis. We limit our analysis to the plane strain problem that is parallel to the $x_1 - x_3$ plane. We employ the following approach for two-dimensional problems:

$$u^k = (u_1^k, 0, u_3^k); k=s,f \quad (3.1)$$

Define dimensionless quantities as:

$$x_i' = \frac{\omega^*}{c_1} x_i, u_i^{k'} = \frac{\rho_0^s \omega^* c_1}{\alpha_0 T_0} u_i^k, t_{ij}^{k'} = \frac{t_{ij}^k}{\alpha_0 T_0}, T' = \frac{T}{T_0}, t' = \omega^* t, \tau_T' = \omega^* \tau_T, \tau_q' = \omega^* \tau_q, \omega' = \frac{\omega}{\omega^*}, \quad (3.2)$$

$$z_l' = \frac{Z_l}{\rho_0^s c_1}, z_5' = \frac{Z_5}{K^*} z_5$$

$$\text{where } \omega^* = \frac{\alpha_1 T_0 c_1^2}{K^*}, c_1^2 = \frac{\lambda + 2\mu}{\rho_0^s} \quad k=s,f; i,j=1,2,3,l=1,2,3,4$$

The potentials ϕ and ψ are related to the displacement components $u_1^k(x_1, x_3, t)$, and $u_3^k(x_1, x_3, t)$ using the Helmholtz decomposition.

$$u_1^k = \frac{\partial \phi^k}{\partial x_1} - \frac{\partial \psi^k}{\partial x_3}, \quad u_3^k = \frac{\partial \phi^k}{\partial x_3} + \frac{\partial \psi^k}{\partial x_1} \quad (3.3)$$

Eqs. (2.1-2.3) with the help of Eqs. (3.1-3.3) becomes

$$\left(\nabla^2 - a_2 \frac{\partial}{\partial t} - \frac{\partial^2}{\partial t^2} \right) \phi^s + \left(-a_1 \nabla^2 + a_2 \frac{\partial}{\partial t} \right) \phi^f - a_3 T = 0 \quad (3.4)$$

$$\left(-\delta_1^2 \nabla^2 + a_2 \frac{\partial}{\partial t} + \frac{\partial^2}{\partial t^2} \right) \psi^s - a_2 \frac{\partial}{\partial t} \psi^f = 0 \quad (3.5)$$

$$\left(-h_1 \nabla^2 + h_3 \frac{\partial}{\partial t} \right) \phi^s + \left(\frac{\partial}{\partial t} \nabla^2 - h_2 \nabla^2 - h_3 \frac{\partial}{\partial t} - h_5 \frac{\partial^2}{\partial t^2} \right) \phi^f - h_4 T = 0 \quad (3.6)$$

$$\left(-h_3 \frac{\partial}{\partial t} \right) \psi^s + \left(-\delta_2^2 \nabla^2 + h_3 \frac{\partial}{\partial t} + h_5 \frac{\partial^2}{\partial t^2} \right) \psi^f = 0 \quad (3.7)$$

$$(d_3 i \omega) \phi^s + (d_4 i \omega) \phi^f + (d_2 + d_5 V^2) T = 0 \quad (3.8)$$

where

$$\delta_1^2 = \frac{\mu}{\lambda + 2\mu}, a_1 = \frac{\sigma^f}{\lambda + 2\mu}, a_2 = \frac{\xi^f}{\rho_0^s \omega^*}, a_4 = \frac{\lambda}{\lambda + 2\mu}, a_3 = (1 - \tau_r), \tau_r = \frac{\gamma^f}{\alpha_0},$$

$$\delta_2^2 = \frac{\mu_v}{\lambda_v + 2\mu_v}, h_1 = \frac{\sigma^f}{\omega^*(\lambda_v + 2\mu_v)}, h_2 = \frac{\sigma^{ff}}{\omega^*(\lambda_v + 2\mu_v)}, h_3 = \frac{\xi^{ff} c_1^2}{\omega^{*2}(\lambda_v + 2\mu_v)},$$

$$h_4 = \frac{(1 + \tau_1)\alpha^f \rho_0^s c_1^2}{\omega^* \alpha_0 (\lambda_v + 2\mu_v)}, h_5 = \frac{\rho_0^f c_1^2}{\omega^*(\lambda_v + 2\mu_v)}, \tau_1 = \frac{\gamma^f}{\alpha^f}, b_1 = \frac{\alpha_0 \zeta^f}{\alpha_1 T_0 (\lambda + 2\mu)}, \tau_2 = \frac{\alpha^f}{\alpha_0}$$

$$b_2 = \frac{\alpha_0 \alpha^f}{\alpha_1 (\lambda + 2\mu)}, b_3 = \frac{\alpha_0^2}{\alpha_1 (\lambda + 2\mu)}, e_1 = \frac{\sigma^{ff}}{\lambda + 2\mu}, e_2 = \frac{\lambda_v \omega^*}{\lambda + 2\mu}, e_3 = \frac{\mu_v}{\lambda + 2\mu},$$

$$d_1 = 1 - \tau_q i \omega - \frac{\tau_q^2}{2!} \omega^2, d_2 = 1 - \tau_T i \omega, d_3 = d_1 b_3 + b_1, d_4 = d_1 b_2 + b_1, d_5 = \frac{-i d_1}{\omega}$$

$$\nabla^2 = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_3^2} \right)$$

We presume that the motion is time-harmonic and that

$$(\phi^s, \phi^f, T, \psi^s, \psi^f) = (\bar{\phi}^s, \bar{\phi}^f, \bar{T}, \bar{\psi}^s, \bar{\psi}^f) e^{i\{k(x_1 \sin \theta - x_3 \cos \theta) - \omega t\}} \quad (3.9)$$

where θ is the angle of inclination, k is wave number

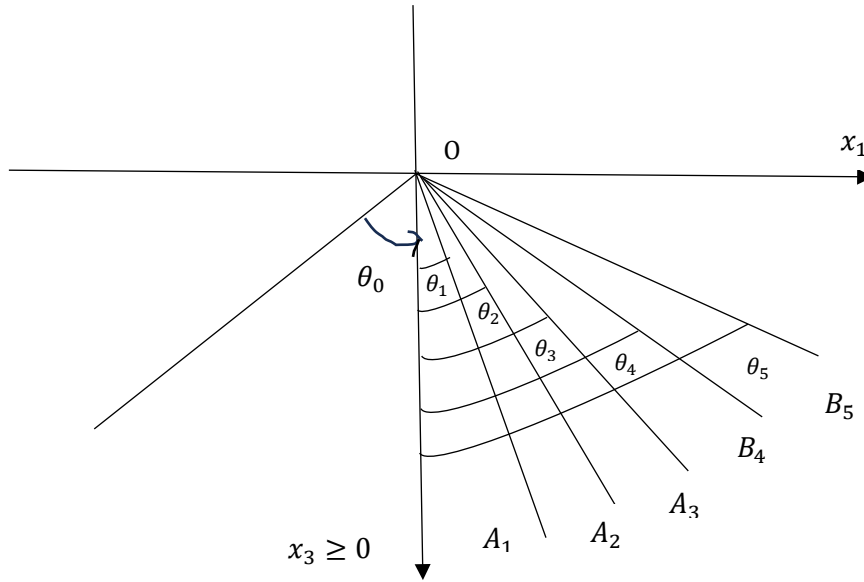


Fig. 1. Geometry of the problem depicting incident and reflected waves in swelling porous thermoelastic half-space

Using Eq. (3.9) in Eqs. (3.4) -(3.8), we can calculate the following:

$$A v^6 + B v^4 + C v^2 + D = 0 \quad (3.10)$$

$$A_1 v^4 + B_1 v^2 + C_1 = 0 \quad (3.11)$$

where the roots of Eq. (3.10) correspond to the velocity of the *Ps*-wave, *Pf*-wave, and *T*-wave, while the roots of Eq. (3.11) give the velocity of the *SVS*-wave and *SVF*-wave.

$$A = \tau_{11} l_2 + \tau_{14} l_4, B = -l_2 \tau_{24} + l_1 \tau_{11} - a_1 l_4 + l_3 \tau_{14} - \frac{a_3}{\omega^2} l_6, D = -\tau_{12} d_2 - a_1 h_1 d_2,$$

$$C = -l_1 + d_2 \tau_{11} \tau_{12} - a_1 l_3 + h_1 d_2 \tau_{14} - \frac{a_3}{\omega^2} l_5, A_1 = \tau_{11} \tau_{16} - \tau_{15} \tau_{14}, B_1 = \tau_{11} \delta_2^2 i \omega - \tau_{16} \delta_1^2, C_1 = -\delta_1^2 \delta_2^2 i \omega, \tau_{12} = i \omega + h_2, \tau_{13} = \tau_{15} + h_5, \tau_{14} = \frac{i a_2}{\omega}, \tau_{11} = 1 + \tau_{14}, \tau_{15} = \frac{i h_3}{\omega},$$

$$\tau_{16} = \tau_{15} - h_5, l_1 = \tau_{12} d_5 + \tau_{13} d_2 + \frac{i d_4 h_4}{\omega}, l_2 = \tau_{13} d_5, l_3 = h_1 d_5 - \tau_{15} d_2 + \frac{i d_3 h_4}{\omega},$$

$$l_4 = -\tau_{15} d_5, l_5 = (h_1 d_4 - \tau_{12} d_3) i \omega, l_6 = -(\tau_{15} d_4 + \tau_{13} d_3) i \omega$$

Making use of Eqs. (3.1-3.3) in Eqs. (2.4-2.5) we obtain

$$t_{33}^s = -a_1 \left(\frac{\partial^2 \phi^f}{\partial x_1^2} + \frac{\partial^2 \phi^f}{\partial x_3^2} \right) + a_4 \left(\frac{\partial^2 \phi^s}{\partial x_1^2} + \frac{\partial^2 \phi^s}{\partial x_3^2} \right) + 2\delta_1^2 \left(\frac{\partial^2 \phi^s}{\partial x_3^2} + \frac{\partial^2 \psi^s}{\partial x_3 \partial x_1} \right) - T \tag{3.12}$$

$$t_{31}^s = \delta_1^2 \left(2 \frac{\partial^2 \phi^s}{\partial x_3 \partial x_1} + \frac{\partial^2 \psi^s}{\partial x_1^2} - \frac{\partial^2 \psi^s}{\partial x_3^2} \right) \tag{3.13}$$

$$t_{33}^f = -a_1 \left(\frac{\partial^2 \phi^s}{\partial x_1^2} + \frac{\partial^2 \phi^s}{\partial x_3^2} \right) - e_1 \left(\frac{\partial^2 \phi^f}{\partial x_1^2} + \frac{\partial^2 \phi^f}{\partial x_3^2} \right) + e_2 \left(\frac{\partial^2 \phi^f}{\partial x_1^2} + \frac{\partial^2 \phi^f}{\partial x_3^2} \right) + 2e_3 \omega^* \left(\frac{\partial^2 \phi^f}{\partial x_3^2} + \frac{\partial^2 \psi^f}{\partial x_3 \partial x_1} \right) - \tau_2 T \tag{3.14}$$

$$t_{31}^f = e_3 \omega^* \left(2 \frac{\partial^2 \phi^f}{\partial x_3 \partial x_1} + \frac{\partial^2 \psi^f}{\partial x_1^2} - \frac{\partial^2 \psi^f}{\partial x_3^2} \right) \tag{3.15}$$

4. Boundary Conditions

The boundary conditions at surface $x_3 = 0$ are

$$\begin{aligned} \text{(i)} \quad t_{33}^s + \omega z_1 u_3^s &= 0 & \text{(ii)} \quad t_{31}^s + \omega z_2 u_1^s &= 0 & \text{(iii)} \quad t_{33}^f + \omega z_3 u_3^f &= 0 \\ \text{(iv)} \quad t_{31}^f + \omega z_4 u_1^f &= 0 & \text{(v)} \quad K^* \frac{\partial T}{\partial x_3} + \omega z_5 T &= 0 \end{aligned} \tag{4.1}$$

where z_1, z_2, z_3, z_4 are impedance parameters having dimension $\frac{Ns}{m^3}$. z_5 is impedance parameter having dimension $\frac{N}{mK}$. We assume the values of $\phi^s, \phi^f, T, \psi^s, \psi^f$ as:

$$\phi^s = \sum A_{0m} e^{i\{k(x_1 \sin \theta_0 - x_3 \cos \theta_0) - \omega t\}} + A_m e^{i\{k(x_1 \sin \theta_m + x_3 \cos \theta_m) - \omega t\}} \tag{4.2}$$

$$\phi^f = \sum \alpha_m (A_{0m} e^{i\{k(x_1 \sin \theta_0 - x_3 \cos \theta_0) - \omega t\}} + A_m e^{i\{k(x_1 \sin \theta_m + x_3 \cos \theta_m) - \omega t\}}) \tag{4.3}$$

$$T = \sum \beta_m (A_{0m} e^{i\{k(x_1 \sin \theta_0 - x_3 \cos \theta_0) - \omega t\}} + A_m e^{i\{k(x_1 \sin \theta_m + x_3 \cos \theta_m) - \omega t\}}) \tag{4.4}$$

$$\psi^s = \sum B_{0n} e^{i\{k(x_1 \sin \theta_0 - x_3 \cos \theta_0) - \omega t\}} + B_n e^{i\{k(x_1 \sin \theta_n + x_3 \cos \theta_n) - \omega t\}} \tag{4.5}$$

$$\psi^f = \sum \gamma_n (B_{0n} e^{i\{k(x_1 \sin \theta_0 - x_3 \cos \theta_0) - \omega t\}} + B_n e^{i\{k(x_1 \sin \theta_n + x_3 \cos \theta_n) - \omega t\}}) \tag{4.6}$$

where $\alpha_m = \frac{(\frac{h_4}{\omega^2})V^2(-1+\tau_{11}V^2) - (\frac{\alpha_3}{\omega^2})V^2(h_1-\tau_{15}V^2)}{(\alpha_1-\tau_{14}V^2)(\frac{-h_4}{\omega^2})V^2 + (\frac{\alpha_3}{\omega^2})V^2(\tau_{12}+\tau_{13}V^2)}$,

$$\beta_m = \frac{(-1+\tau_{11}V^2)(\tau_{12}+\tau_{13}V^2) - (\alpha_1-\tau_{14}V^2)(h_1-\tau_{15}V^2)}{(\alpha_1-\tau_{14}V^2)(\frac{-h_4}{\omega^2})V^2 + (\frac{\alpha_3}{\omega^2})V^2(\tau_{12}+\tau_{13}V^2)}, \gamma_n = \frac{\delta_1^2 - \tau_{11}V^2}{-\tau_{14}V^2} \quad (m=1,2,3; n=3,4)$$

where A_{0m} ($m = 1,2,3$) denote amplitude of incident *Ps*-wave, *Pf*-wave and *T*-wave A_m ($m = 1,2,3$) correspond to reflected *Ps*-wave, *Pf*-wave and *T*-wave, B_{0n} ($n = 3,4$) signify amplitude of incident *SVS*-wave and *SVF*-wave and B_n ($n = 3,4$) associate with the reflected *SVS*-wave and *SVF*-wave.

Snell's Law is denoted as $\frac{\sin \theta_0}{v_0} = \frac{\sin \theta_i}{v_i}$ ($i=1,2,3,4,5$)

where $k_1 v_1 = k_2 v_2 = k_3 v_3 = k_4 v_4 = k_5 v_5 = \omega$

The following relation coefficients (or amplitude ratios) are obtained by applying boundary conditions (4.1) to Eq. (3.3), Eqs. (3.12-3.15).

$$\sum a_{pj} Z_j = g_p, \quad (p,j=1,2,3,4,5) \tag{4.7}$$

$$a_{1i} = \left(\alpha_i a_1 - a_4 - 2\delta_1^2 \left(1 - \left(\frac{v_i}{v_1} \right)^2 \sin^2 \theta_0 \right) - \frac{\beta_i}{k_i^2} \right) \left(\frac{v_1}{v_i} \right)^2 + \frac{v_1^2}{v_i} z_1 \sqrt{1 - \left(\frac{v_i}{v_1} \right)^2 \sin^2 \theta_0}$$

$$g_1 = (-\alpha_1 a_1 + a_4 + 2\delta_1^2 \cos^2 \theta_0) + \frac{\beta_1}{k_1^2} + v_1 z_1 i \cos \theta_0$$

$$a_{1j} = -2\delta_1^2 \sin\theta_0 \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0} \left(\frac{v_1}{v_j}\right) + iz_1 v_1 \sin\theta_0$$

$$a_{2i} = -2\delta_1^2 \sin\theta_0 \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0} \left(\frac{v_1}{v_i}\right) + iz_2 v_1 \sin\theta_0$$

$$a_{2j} = \delta_1^2 \left(-\left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0 + \left(1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0\right) \right) \left(\frac{v_1}{v_j}\right)^2 - \frac{v_1^2}{v_j} iz_2 \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0}$$

$$g_2 = (-2\delta_1^2 \sin\theta_0 \cos\theta_0) - iz_2 v_1 \sin\theta_0$$

$$a_{3i} = \left(a_1 + e_1 \alpha_i + ik_i v_i \alpha_i \left(e_2 + 2e_3 \omega^* \left(1 - \left(\frac{v_i}{v_1}\right)^2 \sin^2\theta_0\right) \right) - \frac{\tau_2 \beta_i}{k_i^2} \right) \left(\frac{v_1}{v_i}\right)^2 + i \alpha_i z_3 \frac{v_1^2}{v_i} \sqrt{1 - \left(\frac{v_i}{v_1}\right)^2 \sin^2\theta_0}$$

$$g_3 = -(a_1 + e_1 \alpha_1 + ik_1 v_1 \alpha_1 (e_2 + 2e_3 \omega^* \cos^2\theta_0)) + \frac{\tau_2 \beta_i}{k_1^2} + v_1 z_3 \alpha_1 i \cos\theta_0$$

$$a_{3j} = ik_j \gamma_j 2e_3 \omega^* v_1 \sin\theta_0 \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0} + iz_3 \gamma_j v_1 \sin\theta_0$$

$$a_{4i} = ik_i \alpha_i 2e_3 \omega^* v_1 \sin\theta_0 \sqrt{1 - \left(\frac{v_i}{v_1}\right)^2 \sin^2\theta_0} + i \frac{v_1^2}{v_i} z_4 \alpha_i \sin\theta_0$$

$$g_4 = ik_1 \alpha_1 2e_3 \omega^* v_1 \sin\theta_0 \cos\theta_0 - i v_1 z_4 \alpha_1 \sin\theta_0$$

$$a_{4j} = e_3 \omega^* \left(ik_j \gamma_j v_j \sin^2\theta_0 + \left(1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0\right) \left(-ik_j \gamma_j \frac{v_1^2}{v_j}\right) \right) - iz_4 \gamma_j \frac{v_1^2}{v_j} \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0}, g_5 = i \frac{\beta_1}{k_1} \cos\theta_0 - z_5 \frac{\beta_1}{k_1} v_1$$

$$a_{5i} = i \frac{\beta_i}{k_i} \left(\frac{v_1}{v_i}\right)^2 \sqrt{1 - \left(\frac{v_i}{v_1}\right)^2 \sin^2\theta_0} + z_5 \frac{\beta_i v_1^2}{k_i v_i}, a_{54} = a_{55} = 0$$

The amplitude ratios of reflected *Ps*, *Pf*, *T*, and *SVS*, *SVF* waves for an incident *Ps* wave are denoted by $Z_i = \frac{A_i}{A_{01}}$ ($i=1,2,3$) and $Z_j = \frac{B_j}{A_{01}}$ ($j=4,5$). In the same way, the amplitude ratios of reflected waves can be determined for the incident *Pf*, *T*, *SVS*, or *SVF* waves.

5. Energy ratios of reflected waves

This section calculates the dissemination of energy amongst reflected waves. In accordance with (Achenbach, 1973), the rate at which energy is transmitted per unit surface area per unit time is presented as

$$P^e = \frac{1}{2} \sum_{k=s,f} \Re((t_{33}^k) \dot{u}_3^k) + \frac{1}{2} \sum_{k=s,f} \Re((t_{31}^k) \dot{u}_1^k) \quad (5.1)$$

The average reflected wave energy at $x_3 = 0$ is given by

$$|E_i| = -\left(\frac{A_i}{A_{01}}\right)^2 \frac{\left(\frac{v_1}{v_i}\right)^2 \sqrt{1 - \left(\frac{v_i}{v_1}\right)^2 \sin^2\theta_0} \left[(\alpha_i a_1 - a_4 - 2\delta_1^2) - \frac{\beta_i}{k_i^2} + r_i \right]}{\cos\theta_0 \left[(\alpha_1 a_1 - a_4 - 2\delta_1^2) - \frac{\beta_1}{k_1^2} + r_1 \right]} \quad (5.2)$$

$$|E_j| = -\left(\frac{B_j}{A_{01}}\right)^2 \frac{\left(\frac{v_1}{v_j}\right)^2 \sqrt{1 - \left(\frac{v_j}{v_1}\right)^2 \sin^2\theta_0} \left((-\delta_1^2 + i\omega e_3 \omega^* \gamma_j^2) \right)}{\cos\theta_0 \left[(\alpha_1 a_1 - a_4 - 2\delta_1^2) - \frac{\beta_1}{k_1^2} + r_1 \right]} \quad (5.3)$$

where, $r_i = \alpha_i (a_1 + e_1 \alpha_i + ik_i \alpha_i v_i e_2 + 2ie_3 \omega^* k_i \alpha_i) - \frac{\tau_2 \beta_i}{k_i^2}$ ($i=1,2,3; j=4,5$)

6. Discussion and numerical outcomes

The following data is used to demonstrate the consequence of the impedance parameter on the energy ratios of reflected Ps , Pf , T , SVS , and SVF waves (Tomar & Goyal, 2013).

Symbol	Value	Unit	Symbol	Value	Unit
λ	6.0×10^9	N/m^2	α^f	0.152×10^6	$N/m^2 K$
μ	9.0×10^9	N/m^2	α_0	0.015×10^6	$N/m^2 K$
λ_v	1.002×10^{-3}	Ns/m^2	γ^f	1.656×10^6	$N/m^2 K$
μ_v	8.88×10^{-4}	Ns/m^2	T	298	K
σ^f	0.03×10^6	N/m^2	ρ_0^s	2.65×10^3	Ns^2/m^4
σ^{ff}	0.291×10^5	N/m^2	ρ_0^f	9.90×10^2	Ns^2/m^4
ξ^{ff}	0.0250×10^6	Ns/m^4	K^*	0.498×10^2	N/sK
α_1	0.03831×10^2	$N/m^2 K^2$	ζ^f	2.15×10^6	N/m^2

Energy ratios for reflected Ps -wave, Pf -wave, T -wave, SVS -wave, and SVF -wave are obtained and presented graphically in Figs. 2(a-e) to 6(a-e) using the aforementioned numerical data for $\tau_T = 0.3 s$ and $\tau_q = 0.4 s$ and impedance parameters $z_1= 10, z_2= 20, z_3= 30, z_4= 40, z_5= 50$. The energy ratios $|E_p|$ ($p = 1, \dots, 5$) of these waves are plotted against the angle of incidence.

7. Specific Situation

For the case in which $\tau_T = 0, \tau_q \neq 0$ and $\tau_q^2 = 0$ the LS-model is used to reduce the results that have been obtained.

The change in energy ratios of reflected waves in the DP (dual phase lag model) and LS model when the Ps wave is incident is illustrated in **Fig. 2(a-e)**. It is noted that the energy ratios of all reflected waves diminish as the angle of incidence increases. For each angle of incidence, the approximate value of E_1 remains unity for both the DP and LS models. Except for E_4 , the DP model's reflected energy ratios are lower than those of the LS model.

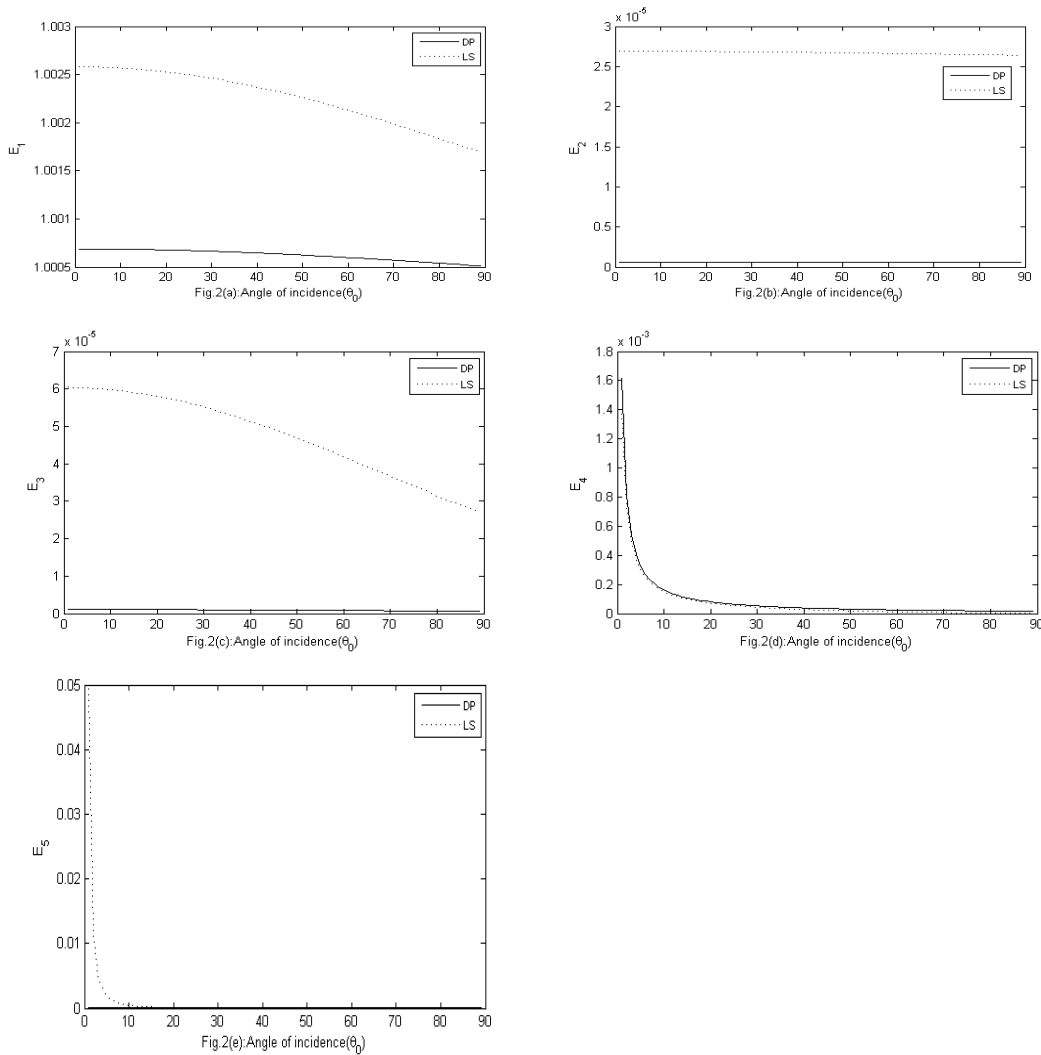


Fig. 2(a-e) illustrates the variation of energy ratios of reflected waves in relation to the angle of incidence when a Ps wave is incident.

Fig. 3(a-e) illustrates the reflected energy ratios that result from the incidence of the *Pf* wave. It is observed that the values of E_2 , E_3 , and E_4 diminish as the angle of incidence increases, while E_1 increases in both the DP and LS models. The energy ratios for E_5 initially decline and then begin to rise as the angle of incidence changes. Additionally, the initial values of E_5 for the DP model are lower than those of the LS model; however, the reverse behaviour is observed later. It is also detected that the energy ratios in the DP model are lower than those in the LS model, with the exception of E_5 .

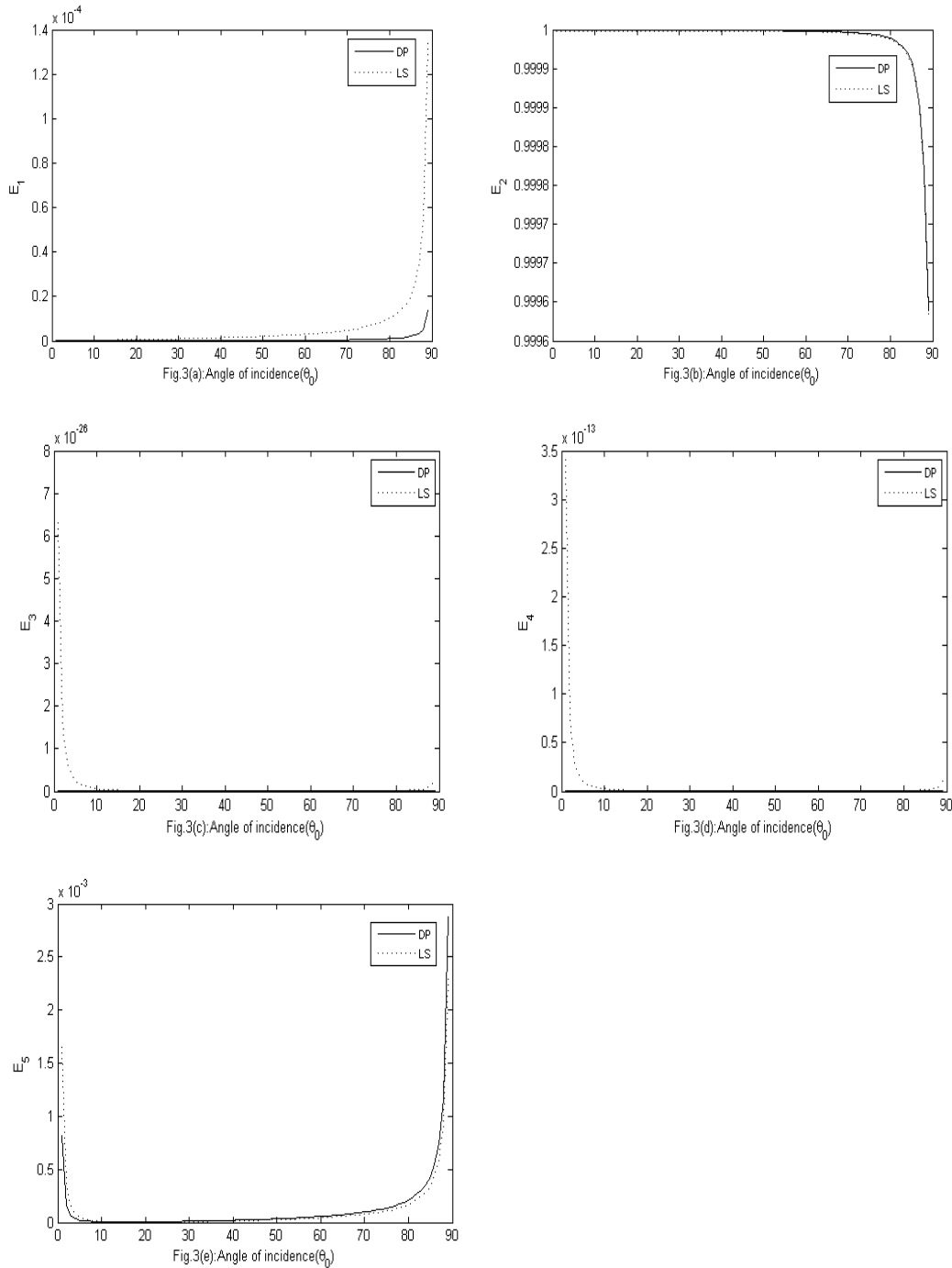


Fig. 3(a-e) illustrates the variation of energy ratios of reflected waves in relation to the angle of incidence when a *Pf* wave is incident.

Fig. 4(a-e) illustrates the variation in reflected energy ratios as a result of the incidence of the *T* wave. Energy ratios in the DP model decrease as the angle of incidence rise, with the exception of E_5 . The energy ratios of the LS model exhibit oscillatory behaviour. In the DP model, energy ratios diminish as the angle of incidence changes, whereas in the LS model, they oscillate in response to the angle of incidence. The energy ratio E_2 in the LS model is lower than the results acquired for the DP model. However, the energy ratio E_3 is greater than the DP model throughout the entire spectrum.

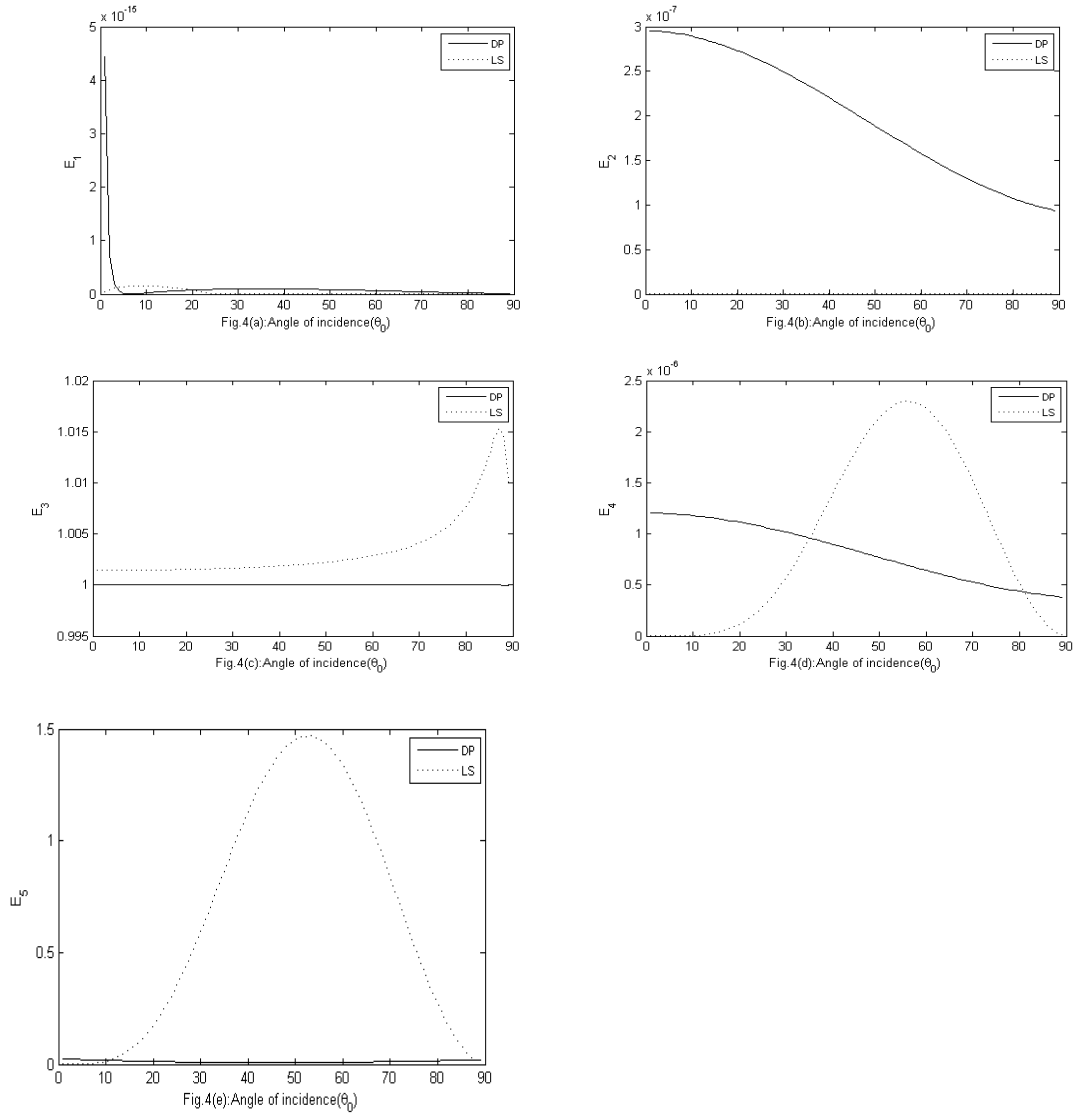
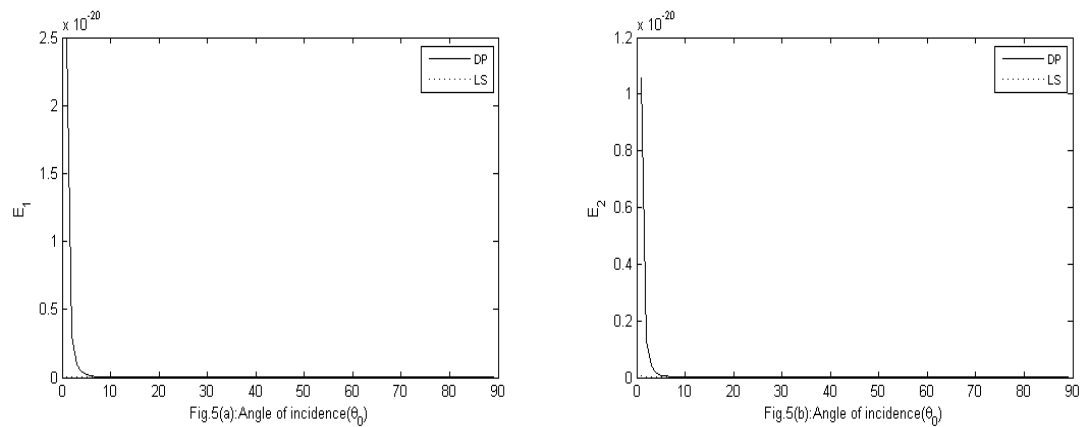


Fig. 4(a-e) illustrates the variation of energy ratios of reflected waves in relation to the angle of incidence when a *T* wave is incident.

The energy ratios of reflected waves for the DP and LS models diminish as the angle of incidence increases when the *SVS* wave is incident, as illustrated in **Fig 5(a-e)**. The energy ratios in the LS model are still lower than the outcomes achieved in the DP model at each angle of occurrence. Also, the values of E_4 for both the DP and LS models decrease and converge to one.



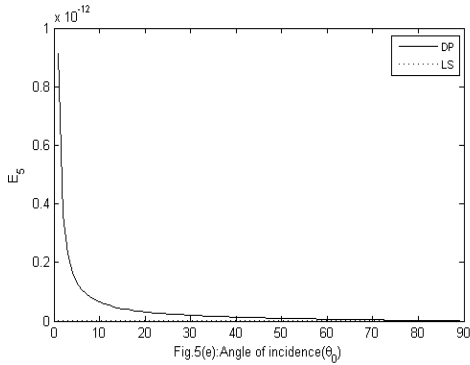
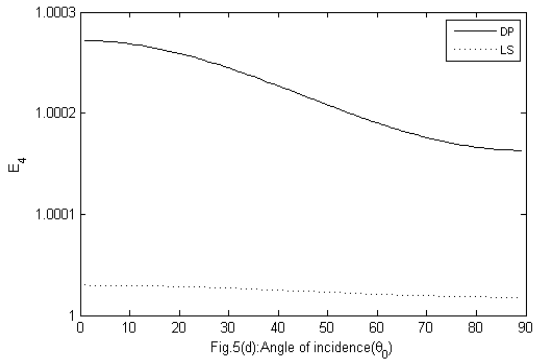
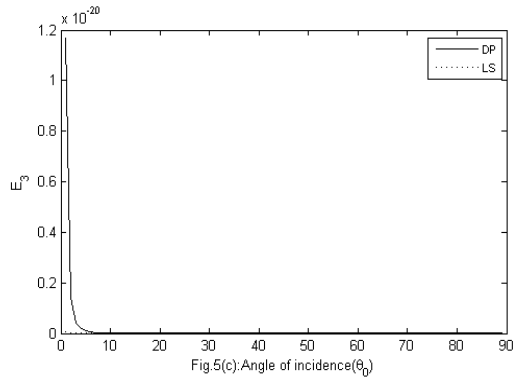
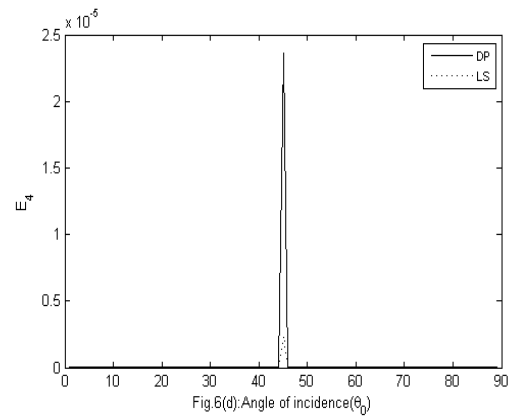
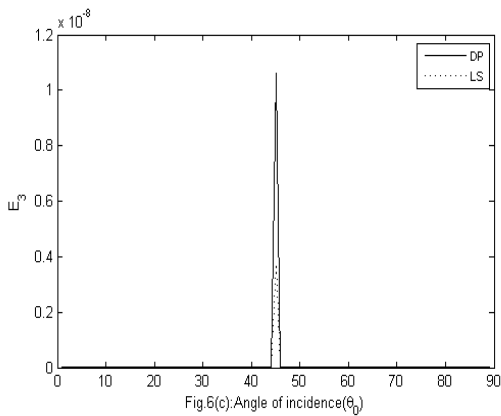
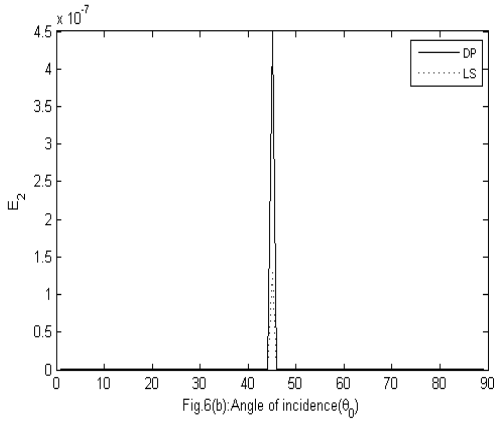
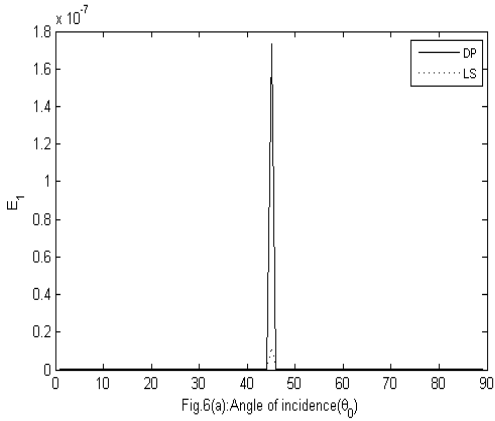


Fig. 5(a-e) illustrates the variation of energy ratios of reflected waves in relation to the angle of incidence when a *SVS* wave is incident.

The energy ratios of the reflected wave are illustrated in Fig 6(a-e) when an *SVF* wave is incident. It has been noted that the energy ratios for the DP model are higher than those obtained for the LS model. The maximal value of E_1 , E_2 , E_3 , and E_4 is achieved at $\theta = 45^\circ$ in both models. The energy ratio E_5 increases with the angle of incidence, and its values remain relatively close to one at each angle of incidence.



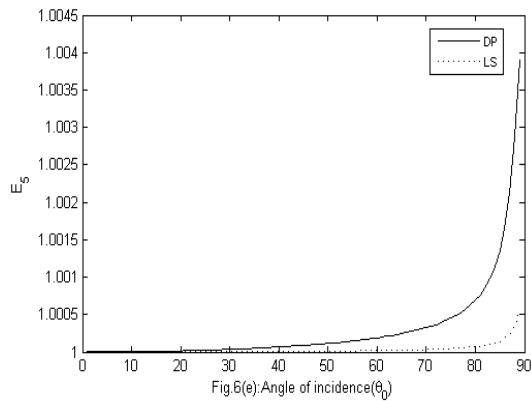


Fig. 6(a-e) illustrates the variation of energy ratios of reflected waves in relation to the angle of incidence when a *SVF* wave is incident.

8. In Conclusion

The investigation focuses on the reflection of plane waves from a porous thermoelastic medium that is enlarging and has a dual phase lag, which is subject to an impedance boundary. There are two longitudinal waves, a thermal wave, and two transversal waves. Amplitude ratios and energy ratios for the dual phase lag model and LS model are compared based on the incidence of each wave. It has been noted that the sum of the energy ratio at each angle of incidence is approximately one, which demonstrates the preservation of the law of conservation of energy. It is also detected that the energy ratios for reflected waves in the DP model are lower than the values obtained for the LS model when *Ps*, *Pf*, and *T* waves are incident. Conversely, the reverse behaviour is observed when transversal waves are incident. Additionally, the energy ratios reach their maximal value at $\theta = 45^\circ$ in both the DP and LS models when the *SVF* wave is incident. These findings may prove advantageous in the investigation of numerous seismological issues.

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